Article 1. Two Automatic Vehicle Identification Equipment Protocols
§ 1700.1. General.
Articles 2 through 5 specify the current automatic vehicle identification (AVI) equipment specifications in use referred to here as the “Title 21 protocol” and Articles 6 through 8 specify new automatic vehicle identification equipment specifications referred to herein as the “6C protocol.”


§ 1700.2. Operation.
All toll facility operators shall have the capability to read and process transponders on the roadway using the 6C protocol no later than January 1, 2019.

The Title 21 and 6C protocols shall operate concurrently.


§ 1700.3. Repeal.
Articles 2 through 5 shall be repealed effective January 1, 2024.

Nothing in these regulations shall preclude the toll facility operators from discontinuing the operation and support of the Title 21 protocol as defined in Articles 2 through 5 at an earlier date if a written request is submitted to and approved by the California Department of Transportation (Caltrans).


Article 2. Summary of Key Compatibility Specifications for Automatic Vehicle Identification Equipment
§ 1700.1701.1. Summary.
The compatibility specifications for automatic vehicle identification (AVI) equipment in Articles 2 through 5 have been developed around two principal components, a reader and a transponder. The minimum role of the reader is to:
1) trigger or activate a transponder.
2) poll the transponder for specific information, and
3) provide an acknowledgement message to the transponder after a valid response to the polling message has been received.

A half-duplex communications system is envisioned where the transponder takes its cues from the reader. The specification is meant to define a standard two-way communications protocol and to further define an initial set of data records. A summary of the key compatibility specifications found in this Chapter Articles 2 through 5 are set forth below:

<table>
<thead>
<tr>
<th>Reader Specifications:</th>
<th>Transponder Specifications:</th>
</tr>
</thead>
<tbody>
<tr>
<td>Reader Trigger Signal:</td>
<td>Technology Type: Modulated Backscatter</td>
</tr>
<tr>
<td>Reader Send Mode (Downlink) Carrier Frequency:</td>
<td>Transponder Antenna Polarization: Horizontal</td>
</tr>
<tr>
<td></td>
<td>Field-of-View: Operation within 90 ° conical angle</td>
</tr>
<tr>
<td>Carrier Modulation:</td>
<td>Location: Front of Vehicle</td>
</tr>
<tr>
<td>Data Bit Rate:</td>
<td>Transponder Send Mode (Uplink) Carrier Frequency:</td>
</tr>
<tr>
<td>No. Data Bits:</td>
<td>Same as Reader Send Mode</td>
</tr>
<tr>
<td>Field Strength at Transponder Antenna:</td>
<td>Carrier Modulation: Subcarrier AM</td>
</tr>
<tr>
<td></td>
<td>Subcarrier AM: FSK</td>
</tr>
<tr>
<td></td>
<td>Subcarrier Frequencies: 600 kHz + 10% and 1200 kHz + 10%</td>
</tr>
<tr>
<td></td>
<td>Data Bit Rate: 300 kbps</td>
</tr>
<tr>
<td></td>
<td>No. Data Bits: Application Specific</td>
</tr>
<tr>
<td>Receiver Field-Strength Threshold:</td>
<td>500 mV/m (minimum)</td>
</tr>
</tbody>
</table>

Note: All mV/m specifications are in RMS voltage.


§ 4701.1701.2. Definition of Technical Terms. 
The following are definitions of technical terms used throughout this Chapter Articles 2 through 5:
(a) AM–Amplitude modulation
(b) ASK–Amplitude shift keying
(c) BCC–Block check character
(d) CRC–Cyclic redundancy check
(e) CW–Continuous wave
(f) EIRP–effective isotropically radiated power = gain x net power
(g) EM–Electromagnetic
(h) FCC–Federal Communications Commission
(i) FSK–Frequency-shift keying
Article 2.03. Introduction
§ 1702.1. Objectives.
This chapter Articles 3 through 5 defines the compatibility requirements for automatic vehicle identification (AVI) equipment. Supplemental agency (e.g., toll authority) specifications will detail the technical, environmental, and operational specifics for each site implementation. The immediate mandate for this compatibility specification is for electronic toll collection.

AVI equipment will essentially consist of two functional elements: vehicle-mounted transponders and fixed-position reader units. The specification is meant to define a standard communications protocol and to further define an initial set of data records. The initial data records are designed for voluntary implementations of electronic toll collection.

It is further envisioned that more complex data records will be developed to handle anonymous transactions, secure funds transfers, information transfers, and other transactions between the reader and the transponder that will be defined as needed. The transponders may have the capability to read and write information. The California Department of Transportation (Caltrans) shall function as the standards monitoring authority to authorize the use of new record types and to assign record type numbers to newly authorized records. Caltrans shall pass this responsibility to an appropriate standards setting organization when one is established and recognized with Caltrans retaining representation in the standards setting organization.

Nothing in these regulations shall preclude the addition of functions and technologies to the transponder and/or reader systems.

§ 1702.2. Organization.  
This chapter consists of four articles. An overview and summary of the key specifications is given in Article 1. Article 2 presents the objectives and definitions for data codes. Articles 3 and 4 provide specifications unique to the reader and transponder respectively.

§ 1703.1702.2. Definitions for Data Codes.  
(a) Agency Code: This 16-bit code field identifies the agency that has authority to conduct the transaction.
(b) Byte Order: Numeric fields shall be transmitted by the most significant bit first. If a numeric field is represented as multiple bytes, the most significant bit of the most significant byte is transmitted first. This document represents the most significant and first transmitted to the left on a line and to the top of a multi line tabulation.
(c) Error Detection Code: The error detection code utilized in the defined records is the CRC-CCITT, with a generator polynomial of \( X^{16} + X^{12} + X^5 + 1 \). This results in a 16-bit BCC transmitted with each data message. The data field protected by the CRC excludes any preceding header in every case.
(d) Filler Bits: Filler bits are used to adjust the data message length to a desired length and shall be set to zero.
(e) Header Code: The header is the first field in each data message for either reader or transponder transmissions, and consists of an 8-bit and a 4-bit word for a total of 12 bits. The header provides a signal that may be used by a receiver to self-synchronize (selsyn) with the data being transmitted - thus the notation selsyn. The selsyn signal has binary and hexadecimal values: 10101010 and AA, respectively. The header code also provides for a unique 4 bit flag that is recognized by a receiver decoder as the end of the header with the data message to follow. The flag signal has binary and hexadecimal values - 1100 and C respectively.
(f) Reader ID Number: This 32-bit field is used to uniquely identify the reader conducting the transaction.
(g) Transaction Record Type Code: This 16-bit code uniquely identified a specific type of valid transaction between a reader and a transponder. This code uniquely defines the transponder message fields and functions permissible with the transaction type specified by the polling message as described in Section 1704.51703.5(e)(1). Hexadecimal numbers 1 through 7FFF are set aside for transponder message structures and 8000 through FFFF are dedicated for reader to transponder message structures.
(h) Transaction Status Code: Used to provide status information to the transponder.
(i) Transponder ID Number: This 32-bit code uniquely identifies which transponder is responding to a polling request or is being acknowledged.

The reader will transmit a RF trigger pulse to activate (turn-on) the transponders. After a time delay, the reader then will transmit an encoded signal, referred to as the polling message which, upon detection and decoding by the transponder, will provide initial information to the transponder including the type of transaction the reader wishes to conduct.

The reader will then transmit an unmodulated CW.RF signal for the transponder to modulate with a data message while backscattering to the reader. The reader may repeat the polling to backscattering sequence until it obtains an error free data message from the transponder. The reader will then transmit an encoded acknowledgement message to the transponder providing status information and requesting that the transponder not respond to the same polling message again for a fixed time period.


§ 1704.2. RF Carrier Frequency.
The RF carrier frequency shall be taken from the 915 MHz + 13 MHz range. The specific frequency and bandwidth depend upon pending FCC assignment.


§ 1704.3. Reader Antenna Specifications.
(a) Reader Antenna Polarizations.
The reader’s transmit and receive antennas shall have predominant EM field components that are co-polarized to the horizontal polarization specified for the transponders’ transmit and receive antennas in section 1705.3. Horizontal, linear, circular, or elliptical polarizations are allowed.
(b) Reader Antenna Location.
The reader’s antenna location is site specific.


§ 1704.4. Reader-To-Transponder Trigger Pulse.
(a) Trigger Pulse Definition.
The reader shall provide a wakeup trigger for the transponder. The trigger shall consist of a 33 microsecond long, RF pulse at the assigned carrier frequency that is modulated with a continuous string of ones. The trigger pulse shall be followed immediately by a delay (i.e., no RF transmission) of 100 microseconds in duration. The wakeup pulse is intended to signal a dormant transponder to fully activate itself.
(b) Trigger Pulse Field Strength.
The required horizontal component of field strength produced by the trigger pulse at the maximum downlink range (site dependent) of the reader shall be greater than 500 mV/m.

§ 4704.51703.5. Reader Communications Protocol.
(a) AM Modulation Scheme.
The downlink (reader-to-transponder) modulation scheme shall be unipolar ASK of the RF carrier using Manchester encoding. A data bit ‘1’ is transmitted by sending an RF pulse during the first half of the bit period and no signal during the second half, while for a ‘0’ data bit the reverse order is used (i.e., no signal during the first half of the bit period and an RF pulse transmission during the second half).
(b) Data Bit Rates.
The data bit rate for reader-to-transponder messages shall be 300 kbps.
(c) Field Strength.
The field strength of a reader data message at the transponder shall be greater than 500 mV/m.
(d) Standard Reader Data Message Format.
The standard portion of a reader data message shall consist of a header and transaction record type code. The subsequent length, data content, and error detection scheme shall then be established by the definition for that transaction record type.
(e) Reader Data Message Formats for AVI.
There may be several reader-to-transponder data message formats. The format is determined by the transaction record type code sent by the reader. The following is the reader-to-transponder message format presently specified for AVI electronic toll collection applications:

(1) Reader Transaction Record Type 1 (Polling Message).
The polling message (which follows the 100 microsecond delay after the trigger signal) tells the transponder the type of transaction the reader wishes to conduct. For AVI electronic toll collection applications, reader transaction record type 1 (polling message) also would identify the agency or toll authority. For AVI applications, the reader-to-transponder type 1 polling message shall be structured using the following ordered data bit fields:

<table>
<thead>
<tr>
<th>Field Definition</th>
<th>No. Bits</th>
<th>Hexadecimal Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>Header Code</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Selsyn</td>
<td>8</td>
<td>AA</td>
</tr>
<tr>
<td>Flag</td>
<td>4</td>
<td>C</td>
</tr>
<tr>
<td>Transaction Record Type Code</td>
<td>16</td>
<td>8000</td>
</tr>
<tr>
<td>Agency Code</td>
<td>16</td>
<td></td>
</tr>
<tr>
<td>Error Detection Code</td>
<td>16</td>
<td></td>
</tr>
<tr>
<td><strong>Total:</strong></td>
<td><strong>60</strong></td>
<td></td>
</tr>
</tbody>
</table>

(2) Reader Transaction Record Type 2 (Acknowledge Message).
A reader-to-transponder acknowledge data message shall be provided to inform specific transponders that they have been successfully processed and to stop responding to further identical reader polling requests. The acknowledge message is used to terminate the transaction, and is only sent if the transaction is successfully completed. Reader
transaction record type 2 (acknowledge message) shall consist of the following ordered data bit fields:

<table>
<thead>
<tr>
<th>Field Definition</th>
<th>No. Bits</th>
<th>Hexadecimal Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>Header</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Selsyn</td>
<td>8</td>
<td>AA</td>
</tr>
<tr>
<td>Flag</td>
<td>4</td>
<td>C</td>
</tr>
<tr>
<td>Transaction Record Type</td>
<td>16</td>
<td>C000</td>
</tr>
<tr>
<td>Transponder ID Number</td>
<td>32</td>
<td></td>
</tr>
<tr>
<td>Reader ID Number</td>
<td>32</td>
<td></td>
</tr>
<tr>
<td>Transaction Status Code</td>
<td>16</td>
<td></td>
</tr>
<tr>
<td>Error Detection Code</td>
<td>16</td>
<td></td>
</tr>
<tr>
<td>Total</td>
<td></td>
<td>124</td>
</tr>
</tbody>
</table>

(f) Reader End-of-Message Frame.
The end-of-message signal for reader-to-transponder data messages shall consist of a minimum of 10 microseconds of no RF carrier signal. Transponder decoders shall have the ability to detect this condition as an invalid Manchester code.


§ 4704.61703.6. Reader Field Strength for Modulated Backscattering.
The electric field strength produced by a reader is a function of the EIRP. The EIRP required to detect a modulated backscattered RF signal from a transponder with a reasonably high signal-to-noise ratio is determined by the maximum range to the transponder and the detection sensitivity of the reader receiver plus any gain margin. If the overall gain characteristics of the transponder were held constant, the required EIRP then becomes site dependent.

The electric field strength to accomplish modulated backscattering is expected to be lower than that required for triggering a transponder or for sending a reader data message. Sensitive reader receivers likely will be necessary, however, such as that obtained with homodyne or heterodyne technology.


Article 45. Transponder Specifications
§ 4705.41704.1. General Description.
Transponders will be encoded with unique identification data together with other coded data as described in this section. On passing through any AVI reader zone, the transponder will provide the coded data to the reader only on receipt of a valid reader polling command. Transponders must be capable of being turned on and off as specified herein. Transponders must be capable of
two-way data communications. Transponders may be portable. The transponders may have the capability to read and write information.


§ 1705.21704.2 Transponder RF Carrier Frequency. The transponder RF carrier frequency in a backscatter system is identical to that used by the reader; the frequency will be in the range of 915 MHz + 13 MHz. The transponder shall be capable of operating over the full + 13 MHz band to allow site flexibility in reader implementation.


§ 1705.31704.3 Transponder Transmit and Receive Antennas. (a) Antenna Polarizations. The transponder transmit and receive antennas shall have EM field components that are predominantly horizontally polarized transverse to normal traffic flow. Horizontal, linear, circular or elliptical polarizations are allowed. (b) Antenna Field of Views. The transponder transmit and receive antennas shall have a field of view which is a 90° cone in front of the vehicle. The projection of the horizontal component of the cone's axis shall be parallel to the lane and the vertical component of the cone's axis shall be 35° horizontal.


§ 1705.41704.4 Transponder Activation. (a) Activation Timing. Within 1 millisecond of entry into the reader's modulated RF field, a transponder shall be fully activated and ready to decode the polling message from the reader within 100 microseconds of receipt of a 33 microsecond long modulated RF trigger pulse from the reader. (b) Activation Timing for Battery Power Management. As an alternative to §1705.41704.4(a), a delay of 20 additional milliseconds is permissible for a transponder using multiple-stage activation to conserve battery life. Within 21 milliseconds of entry into the reader's modulated RF field, such a transponder shall be fully activated and ready to decode the polling message from the reader within 100 microseconds of receipt of a 33 microsecond long modulated trigger pulse from the reader. (c) Activation Field Strength. The transponder receiver shall be capable of recognizing and acting on a trigger signal and polling message when the free-space field strength at the transponder location exceeds 550 mV/m and will not respond to field strengths below 450 mV/m (electric field strengths are to be measured in free-space and in the absence of any vehicle). After completion of the polling
message, the transponder shall begin modulating and backscattering RF with continuous zero bits. One hundred microseconds after completion of the polling message, the transponder shall begin transmitting its message. If a newly activated transponder does not immediately receive a polling message, it shall remain activated and ready to receive a subsequent reader message for at least 20 milliseconds.


§ 1705.51704.5. Transponder Communications Protocol.
(a) Subcarrier Modulation Scheme.
The transponder-to-reader (uplink) modulation scheme shall be amplitude modulation of an RF carrier backscatter created by varying the reflecting cross section of the antenna as seen by the incident carrier signal. The antenna cross section shall be varied between upper and lower limits with a 50 percent duty cycle and rise and fall times of less than 75 nanoseconds. The transponder baseband message signal shall modulate the subcarrier using FSK modulation with a center frequency of 900 kHz and frequency deviation of + 300 kHz. The lower and upper subcarrier frequencies correspond to data bits ‘0’ and ‘1’ respectively. The message information is conveyed by the subcarrier modulation frequencies of the transponder backscattered signal and not by amplitude or phase.
(b) Data Bit Rates.
The data bit rate for transponder-to-reader data messages shall be 300 kbps.
(c) Field Strength.
The field strength at which a transponder data message is transmitted using backscatter technology is dependent upon the incident field strength from the reader, the transponder receive and transmit antenna gains, and any RF gain internal to the transponder. The transponder and antenna gain taken together shall effect a change in the backscattering cross section of between 45 and 100 square centimeters.
(d) Standard Transponder Data Message Format.
The standard portion of a transponder data message shall consist of a header and transaction record type code. The subsequent length, data content, and error detection scheme shall then be established by the definition for that transaction record type.
(e) Transponder Data Message Formats for AVI Toll Collection.
There may be numerous transponder-to-reader data message formats. The format is determined by the transaction record type code sent by the transponder. The following is the reader-to-transponder message format presently specified for AVI electronic toll collection applications:
(1) Transponder Transaction Type 1 (Data Message).
Transponder transaction type 1 (data message) allows for unencrypted transponder ID numbers to be transmitted. Type 1 (data messages) shall be structured using the following ordered data bit fields:
<table>
<thead>
<tr>
<th>Field Definition</th>
<th>No. Bits</th>
<th>Hexadecimal Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>Header Code</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Selsyn</td>
<td>8</td>
<td>AA</td>
</tr>
<tr>
<td>Flag</td>
<td>4</td>
<td>C</td>
</tr>
<tr>
<td>Transaction Record Type Code</td>
<td>16</td>
<td>1</td>
</tr>
<tr>
<td>Transponder ID Number</td>
<td>32</td>
<td></td>
</tr>
<tr>
<td>Error Detection Code</td>
<td>16</td>
<td></td>
</tr>
<tr>
<td>Total:</td>
<td>76</td>
<td></td>
</tr>
</tbody>
</table>

(f) Transponder End-of-Message Frame
The end-of-message signal for transponder data messages shall consist of a minimum of 10 microseconds of with no modulation.


§ 1705.6 1704.6. Transponder Response to Reader Acknowledge Message.
The transponder shall discontinue responding to identical reader polling requests for a period of 10 seconds once a valid reader acknowledgement message has been received. The transponder shall, however, respond to polling messages that are not identical to the polling messages that lead to the valid acknowledgement.


§ 1705.7 1704.7. Multiple Transponder Responses to a Reader Polling Message.
Each transponder data message transmittal must be in response to a reader polling message.


§ 1705.8 1704.8. Transponder Positioning.
Transponders shall be positioned at the front of the vehicle with a clear line of sight to the reader antenna without degrading the performance of the reader-transponder system below minimum specified standards. As a minimum, transponders shall operate up to a maximum of 76cm (30”) offset from the longitudinal center line of the vehicle. The front of the vehicle shall be defined as that portion of the vehicle from the driver's eyes forward.


§ 1705.1. Definition of Terms.
The following are definitions of terms used throughout Articles 6 through 8:

(a) Reader—A device with associated transmit and receive (Tx/Rx) antenna(s), and modulation and demodulation hardware and software.
(b) RF—Radio frequency
(c) Transponders—Electronic devices that contain information which can be communicated to the reader. The transponders may have the capability to store new or modified data received from a reader.
(d) CTOC—California Toll Operators Committee—Collaborative organization composed of California's toll facility operators/owners. CTOC is the primary resource for interoperability and coordination among tolling facilities, and education and advocacy regarding tolling in California.


Article 7. Introduction

§ 1706.1. Objectives.
Articles 7 through 8 define the compatibility requirements for AVI equipment. The mandate for this compatibility specification is for electronic toll collection.

Nothing in these regulations shall preclude the addition of functions and technologies to the transponder and/or reader systems.


Article 8. Reader and Transponder Specifications

§ 1707.1. General.
The automatic vehicle identification equipment shall be compliant with Type C of the International Standards Organization document(s):


Or


Or
Information technology—Radio frequency identification for item management—Part 63:
Parameters for air interface communications at 860 MHz to 960 MHz Type C.


Supplemental toll facility operator specifications may detail the optional functions, technical specifications, environmental, operational and other specific needs for each site installation.

All readers shall operate with any transponder model that meets the requirements in this Article.

All toll facility operators and suppliers collecting any information shall observe and follow all applicable legal authority regarding intellectual property.